

Inertial and Coriolis Effects on Oscillatory Flow in a Horizontal Dendrite Layer

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Abstract

Flow instability due to oscillatory modes of disturbances in a horizontal dendrite layer during alloy solidification is investigated under an external constraint of rotation. The flow in the dendrite layer, which is modeled as flow in a porous layer under the Darcy's law but with the inertial effects included, is assumed to rotate about the vertical axis at a constant angular velocity. The investigation is an extension of the work in Riahi (2003), which was for the case in the absence of the inertial effects. Results of the stability analyses indicate, in particular, that the Coriolis effect can enhance the physical domain for the oscillatory flow, while the inertial effect tends to reduce such domain. Sufficiently strong inertial effect can eliminate presence of the oscillatory mode only for the rotation rate beyond some value.

Key words: rotating convection, dendrite layer, solidification, oscillatory convection, oscillatory instability, inertial flow, mushy layers, stability analysis

Nomenclature

Latin symbols

a : horizontal wave number

a_1 : x -component of \mathbf{a}

a_c : critical a

\tilde{C} : dimensional composition

C_e : eutectic composition

C_r : a concentration ratio

d : dendrite layer thickness

G : $1+S/C$

i : pure imaginary number

K_I : a permeability parameter

k_s : solute diffusivity

L_a : latent heat of solidification

M : liquidus slope

\tilde{P} : modified pressure

\mathbf{a} : horizontal wave number vector

a_2 : y -component of \mathbf{a}

C : scaled concentration ratio

C_0 : far field composition

C_I : specific heat per unit volume

C_S : composition of dendrites

g : acceleration due to gravity

G_I : $(G-1)/(CG^2)$

K : a permeability ratio

k : thermal diffusivity

L : An inertial parameter

\tilde{L} : An inertial parameter

P : scaled modified pressure

P_0 : a constant

P_B : modified basic pressure	R : scaled Rayleigh number
\tilde{R} : Rayleigh number	R_c : critical R
S : scaled Stefan number	S_t : Stefan number
t : scaled time variable	T : Coriolis parameter
\tilde{t} : time variable	T_e : eutectic temperature
T_L : liquidus temperature	T_∞ : far field temperature
\mathbf{u} : scaled volume flux per unit area	\mathbf{U} : velocity vector
$\tilde{\mathbf{u}}$: volume flux per unit area	\tilde{u} : x -component of $\tilde{\mathbf{u}}$
V : poloidal function for \mathbf{u}	V_0 : solidification speed
\tilde{v} : y -component of \mathbf{u}	\tilde{w} : z -component of $\tilde{\mathbf{u}}$
x : scaled horizontal variable	\mathbf{x} : unit vector along x -axis
\tilde{x} : horizontal variable	\tilde{y} : scaled horizontal variable
\mathbf{y} : unit vector along y -axis	y : horizontal variable
z : scaled vertical variable	\mathbf{z} : unit vector along z -axis
\tilde{z} : vertical variable	
<i>Greek symbols</i>	
α^* : thermal expansion coefficient	β^* : solute expansion coefficient
β : $\beta^* - M\alpha^*$	ΔC : $C_0 - C_e$
ΔT : $T_L(C_0) - T_e$	Δ : horizontal Laplacian operator
δ : dimensionless depth of the porous layer	∇ : gradient operator
$\tilde{\theta}$: temperature	θ_B : basic temperature
θ : perturbation temperature	θ_∞ : $T_\infty / \Delta T$
ν : kinematic viscosity	Ω : rotation rate
Π : permeability	$\Pi(0)$: a reference permeability
ϕ : perturbation to solid fraction	ϕ_B : basic solid fraction
$\tilde{\phi}$: local solid fraction	ρ_0 : a reference density
σ : complex growth rate of disturbance	σ_i : disturbance frequency
σ_r : real growth rate of disturbance	ψ : toroidal function for \mathbf{u}

1. Introduction

The problem studied in this paper and in Riahi (2003), which is hereafter referred to as R03, is based on the conditions considered by Anderson and Worster (1996) who studied the problem of the solidification of a binary alloy in a mushy layer, which was treated as a porous layer, and analyzed the linear stability of a motionless state to identify an oscillatory convective mode of instability. Their system was under no rotational constraint, and their investigation was based on the earlier mushy-layer model of Amberg and Homsy (1993). A near-eutectic approximation was employed and the limit of large far-field temperature was considered. Such asymptotic limits allowed them to examine the dynamics of the mushy layer in the form of small deviation from the classical system of convection in a horizontal porous layer of constant permeability. They also considered the limit of large Stefan number, which enabled them to reach a domain for the existence of the oscillatory instability.

Recently R03 extended the linear model treated by Anderson and Worster (1996) by taking into account the effect of rotation due to the Coriolis-force term in the momentum-Darcy equation and examined presence oscillatory mode versus the stationary mode, and he obtained some new results. Similar to the work in Anderson and Worster (1996), it was assumed that inertial terms in the momentum-Darcy equation were negligibly small and, thus, the effects of such terms were totally discarded. The expressions for various quantities were found to be affected by the presence of rotation and certain new qualitative results due to the rotational effect were reported. For example, in the presence of rotation it was found that, in contrast to the stationary mode, the most critical oscillatory mode may be able to reduce the tendency for the chimney formation in the mushy layer. Information about chimney formation can be important in the industrial crystal growth processes where it is of interest to find ways to reduce the undesirable effects of the chimney convection during the alloy solidification since presence of chimney convection is known to lead to imperfections in the final produced crystals, which can significantly reduce the quality of the solidified materials.

The only other studies on oscillatory convection in a rotating dendrite layer are those due to Guba and Boda (1998) and Govender and Vadasz (2002). Guba and Boda (1998) studied the effect of rotation on the linear problem of convection in the absence of inertia effects in a dendrite layer during the directional solidification of a binary alloy, where such layer often is referred to in this area as a mushy layer, and their investigation also did not take into account the interaction between the local solid fraction and the flow associated with the Coriolis term. Their main result was that depending on the values of the parameters, the oscillatory mode can be more critical than the stationary mode or vice versa. Govender and Vadasz (2002) considered the problem of two-dimensional oscillatory convection in a rotating mushy layer. The momentum-Darcy equation was extended only to include the time derivative and the Coriolis terms. The authors did not take into account the presence of the interactions between the local solid fraction and the flow associated with the Coriolis term, and their weakly nonlinear analysis was based on the zero-order limit of the mushy layer thickness. The main result of the study was that two-dimensional oscillatory flow was supercritical.

In the present paper we consider the linear problem for the dendrite system again under the external constraint of rotation, and we examine the properties of the oscillatory mode further by including the interaction between the local solid fraction and the flow associated with the Coriolis term and following Vadasz (1998) to include the time-derivative inertial term in the momentum-Darcy equation. It should be noted that due to the linearity and the zero-basic volume flux of the present problem (R03), the nonlinear inertial term has no contribution in the momentum-Darcy equation even if the nonlinear inertial terms have not been discarded in the full non-linear system. We find some interesting results about the effects of inertial and Coriolis terms on the oscillatory mode. In particular, we find that the presence of the inertial term can have significant effects on the existence of the oscillatory mode or on the value of the period of oscillation of such mode, and rotation effect can enhance such effects. However, rotational effect can also have an opposing effect in the sense that it enhances the domain of the oscillatory mode,

while the inertial effect reduces such domain. The effect of interaction between the local solid fraction and the flow associated with the Coriolis term was found to be stabilizing.

About the motivation of the present study and the applicability of the present results, it should be noted that understanding the rotational effects on the convective flow instabilities in the dendrite layer, which can be formed adjacent to the crystal interface in an alloy system where the inertial effects are not negligible (Vadasz, 1998), are of interest in both geophysical and engineering areas. Understanding the roles and effects of the Coriolis force on the dynamics of a porous layer adjacent to the earth's inner core interface is important in geophysics and for the understanding the geodynamo. In industrial crystal growth processes it has been desirable to impose certain external constraints such as rotation, in an optimized manner upon the system, in order to reduce the effects of such instabilities, which can lead to micro-defect density in the crystal and, thus, reduce the quality of the produced crystal.

It should be noted that the model considered in R03 as well as the present one, which takes into account the rotational effects through the presence of the Coriolis force only, is relevant both in the geophysical applications where the centrifugal mode of convection is insignificant and in the engineering areas where the neglect of the centrifugal effect can be justified under the present assumption that the gravitational buoyancy is much larger than the centrifugal force.

2. Formulation

We consider a binary alloy melt that is cooled from below and is solidified at a constant speed V_0 . The solidifying system is assumed to be rotating at a constant speed Ω about the vertical direction, anti-parallel to the gravity vector. Following Amberg and Homsy (1993) and Anderson and Worster (1996), we consider the dendrite layer of thickness d adjacent and above the solidification front to be physically isolated from the overlying liquid and the underlying solid zones. The overlying liquid is assumed to have a composition $C_0 > C_e$ and a temperature $T_\infty > T_L(C_0)$ far above the mushy layer, where C_e is the eutectic composition, $T_L(\tilde{C})$ is the liquidus temperature of the alloy and \tilde{C} is the composition. Thus, it is assumed that the horizontal mushy layer is bounded from above and below by rigid and isothermal boundaries. We consider the solidification system in a moving frame of reference $o\tilde{x}\tilde{y}\tilde{z}$, whose origin lies on the solidification front, translating at the speed V_0 with the solidification front in the positive \tilde{z} -direction and rotating with the speed Ω about the \tilde{z} -axis.

It should be noted that no double-diffusive effects are present in the present one-layer mushy zone model since such mushy layer is assumed to be in local thermodynamic equilibrium and, thus,

$$\tilde{T} = T_L(C_0) + M(\tilde{C} - C_0),$$

where \tilde{T} is the temperature and M is the slope of the liquidus (Anderson and Worster, 1996). The dendrite layer is treated appropriately as a porous layer (Fowler, 1985; Worster, 1992), where solid dendrites and liquid coexist, and Darcy's law is adopted.

Next, we consider the equations for momentum, continuity, heat and solute for the flow in the mushy layer in the moving frame. The equations are non-dimensionalized by using V_0 , k/V_0 , k/V_0^2 , $\beta\Delta C\rho_0 gk/V_0$, ΔC and ΔT as scaled for velocity, length, time, pressure, solute and temperature, respectively. Here k is the thermal diffusivity, ρ_0 is a reference (constant) density, $\beta = \beta^* - M\alpha^*$, α^* and β^* are the expansion coefficients for the heat and solute respectively and M is assumed to be constant, $\Delta C = C_0 - C_e$, $\Delta T = T_L(C_0) - T_e$ and T_e is the eutectic temperature. The non-dimensional form of the equations for momentum, continuity, temperature and solute concentration in the mushy layer are

$$\{[\tilde{L}/(1-\tilde{\phi})](\partial/\partial\tilde{t} - \partial/\partial\tilde{z}) + K(\tilde{\phi})\}\tilde{\mathbf{u}} = -\nabla\tilde{P} - \tilde{R}\tilde{\theta}\mathbf{z} + T\tilde{\mathbf{u}} \times \mathbf{z} / (1-\tilde{\phi}), \quad (1a)$$

$$\nabla \cdot \tilde{\mathbf{u}} = 0, \quad (1b)$$

$$(\partial/\partial\tilde{t} - \partial/\partial\tilde{z})(\tilde{\theta} - S_t\tilde{\phi}) + \tilde{\mathbf{u}} \cdot \nabla\tilde{\theta} = \nabla^2\tilde{\theta}, \quad (1c)$$

$$(\partial/\partial\tilde{t} - \partial/\partial\tilde{z})[(1-\tilde{\phi})\tilde{\theta} + C_r\tilde{\phi}] + \tilde{\mathbf{u}} \cdot \nabla\tilde{\theta} = 0, \quad (1d)$$

where $\tilde{\mathbf{u}} = \tilde{u}\mathbf{x} + \tilde{v}\mathbf{y} + \tilde{w}\mathbf{z} = (1-\tilde{\phi})\mathbf{U}$ is the volume flux per unit area (Worster, 1992), \mathbf{U} is velocity vector, \tilde{u} and \tilde{v} are the horizontal components of $\tilde{\mathbf{u}}$ along the \tilde{x} - and \tilde{y} -directions, respectively, \mathbf{x} and \mathbf{y} are unit vectors along the positive \tilde{x} - and \tilde{y} -directions, \tilde{w} is the vertical component of $\tilde{\mathbf{u}}$ along the \tilde{z} -direction, \mathbf{z} is a unit vector along the positive \tilde{z} -direction, \tilde{P} is the modified pressure, $\tilde{\theta}$ is the non-dimensional composition (or equivalently temperature), $\tilde{\theta} = [\tilde{T} - T_L(C_0)] / \Delta T = (\tilde{C} - C_0) / \Delta C$, \tilde{t} is the time variable, $\tilde{\phi}$ is the local solid fraction, $\tilde{R} = \beta\Delta Cg\Pi(0)/(V_0\nu)$ is the Rayleigh number, $\Pi(0)$ is reference value at $\tilde{\phi} = 0$ of the permeability $\Pi(\tilde{\phi})$ of the porous medium, ν is the kinematic viscosity, g is acceleration due to gravity, $K(\tilde{\phi}) \equiv \Pi(0)/\Pi(\tilde{\phi})$, $S_t = L_a/(C_l\Delta T)$ is the Stefan number, C_l is the specific heat per unit volume, L_a is the latent heat of solidification per unit volume, $C_r = (C_s - C_0) / \Delta C$ is a concentration ratio, C_s is the composition of the solid-phase forming the dendrites, $\tilde{L} = V_0^2\Pi(0)/(k\nu)$ is an Inertial type of parameter and $T = 2\Omega\Pi(0)/\nu$ is the Coriolis parameter. The equation (1d) is based on the limit of sufficiently large value of the Lewis number k/k_s (Anderson and Worster 1996), where k_s is the solute diffusivity.

The governing equations (1a)-(1d) are subject to the following boundary conditions (Amberg and Homsy, 1993)

$$\tilde{\theta} + 1 = \tilde{w} = 0 \quad \text{at } z = 0, \quad (2a)$$

$$\tilde{\theta} = \tilde{w} = \tilde{\phi} = 0 \quad \text{at } z = \delta, \quad (2b)$$

where $\delta = dV_0/k$ is the dimensionless depth of the layer.

Following Anderson and Worster (1996) in reducing the model asymptotically, we assume the following rescaling in the limit of sufficiently small δ :

$$C_r = C / \delta, S_r = S / \delta, L = \tilde{L} / \delta^2, \delta \ll 1, \quad (3a)$$

$$(\tilde{x}, \tilde{y}, \tilde{z}) = \delta(x, y, z), \quad \tilde{t} = \delta^2 t, \quad R^2 = \delta \tilde{R}, \quad (3b)$$

$$\tilde{\mathbf{u}} = R\mathbf{u} / \delta, \quad \tilde{P} = RP, \quad (3c)$$

where C and S are order one quantities as $\delta \rightarrow 0$. As discussed in Anderson and Worster (1996), the assumption of thin mushy layer ($\delta \ll 1$) is associated with the large non-dimensional far-field temperature $\theta_\infty = T_\infty / \Delta T \gg 1$, which can occur when the initial \tilde{C} is close to C_e . The assumption of order one quantity C corresponds to the near-eutectic approximation (Fowler, 1985), which allows one to describe the dendrite layer as a porous layer of constant permeability to the leading order. The assumption of order one quantity S allowed Anderson and Worster (1996) to detect a new oscillatory instability from their analytical mushy-layer model.

The rescaling (3a)-(3c) are then used in (1a)-(1d) and (2a)-(2b). The resulting system of equations and boundary conditions admits a motionless basic state, which is steady and horizontally uniform. The basic state solution, denoted by subscript 'B' is given below in terms of the asymptotic expansions for $\delta \ll 1$:

$$\theta_B = (z-1) - \delta G(z^2 - z)/2 + \dots \quad (4a)$$

$$\phi_B = -\delta(z-1)/C + \delta^2[-(z-1)^2/C^2 + G(z^2 - z)/(2C)] + \dots, \quad (4b)$$

$$P_B = P_0 - R[(z^2/2 - z) - \delta G(z^3/2 - z^2/2)/2 + \dots], \quad (4c)$$

where P_0 is a constant and $G \equiv S/C + 1$. Since $\tilde{\phi}$ is expected to be small, according to the results (4b), the following expansion for $K(\tilde{\phi})$ will be implemented later in the governing system:

$$K(\tilde{\phi}) = 1 + K_1 \tilde{\phi} + K_2 \tilde{\phi}^2 + \dots, \quad (5)$$

where the coefficients K_1 and K_2 are constants.

For the analysis to be presented in the next section, it was found convenient to use the general representation

$$\mathbf{u} = \nabla \times (\nabla \times \mathbf{z}V) + \nabla \times \mathbf{z}\psi \quad (6)$$

for the divergence-free vector field \mathbf{u} (Chandrasekhar, 1961). Here V and ψ are the poloidal and toroidal functions for \mathbf{u} , respectively. Taking the vertical components of the curl and the double-curl of the Darcy's momentum equation (1a) and using (3)-(6) in (1)-

(2), we find the following leading order system for the dependent variables of the infinitesimal disturbances superimposed on the basic state (4):

$$[1+\delta(1-z)/C]L(\partial/\partial t-\delta\partial/\partial z)\nabla^2\Delta_2V+\Delta_2\nabla^2\{[1+K_I\delta(1-z)/C]V\}+(\delta K_I/C)\Delta_2\partial V/\partial z-R\Delta_2\theta+T\Delta_2\partial/\partial z\{\psi[1+\delta(1-z)/C]\}-(\delta^3/C)L(\partial/\partial t-\delta\partial/\partial z)\Delta_2V=0, \quad (7a)$$

$$[1+\delta(1-z)/C]L\Delta_2(\partial/\partial t-\delta\partial/\partial z)\psi+\Delta_2\{[1+K_I\delta(1-z)/C]\psi\}-T(\Delta_2\partial V/\partial z)[1+(1-z)/C]=0, \quad (7b)$$

$$(\partial/\partial t-\delta\partial/\partial z)[- \theta+(S/\delta)\phi]+R[1+\delta G(1-2z)/2]\Delta_2V+\nabla^2\theta=0, \quad (7c)$$

$$(-\partial/\partial t+\delta\partial/\partial z)\{[1-\delta(1-z)/C]\theta+[(1-z)+\delta G(z^2-z)/2]\phi+(C/\delta)\phi\}+[1+\delta G(1-2z)/2]\Delta_2V=0, \quad (7d)$$

$$\theta=V=0 \quad \text{at } z=0, \quad (7e)$$

$$\theta=V=\phi=0 \quad \text{at } z=1, \quad (7f)$$

where

$$\Delta_2\equiv\partial^2/\partial x^2+\partial^2/\partial y^2 \quad (7g)$$

and

$$(\theta,\phi)=(\tilde{\theta}-\theta_B, \tilde{\phi}-\phi_B). \quad (7h)$$

3. Analysis

We seek normal mode type solution of the form

$$(V,\psi,\theta,\phi)=[V'(z), \psi'(z), \theta'(z), \phi'(z)]\exp(\sigma t+i \mathbf{a} \cdot \mathbf{r}), \quad (8)$$

where $\sigma=\sigma_r+i\sigma_i$ is the complex growth rate, i is the pure imaginary number ($\sqrt{-1}$), σ_r is the real growth rate, σ_i is the frequency of the disturbances, $\mathbf{r}=(x, y)$ is the horizontal position vector and $\mathbf{a}=(a_1, a_2)$ is the horizontal wave number vector of the disturbances. Here a_1 and a_2 are the x and y components of \mathbf{a} , respectively. Using (8) in (7), we find the system of ordinary differential equations and boundary conditions for the z -dependent coefficients V' , ψ' , θ' and ϕ' .

Next, presence of small parameter δ in the above System for the z -dependent coefficients suggests the following expansions of the dependent variables and parameters in powers of δ :

$$(V', \psi', \theta', \phi', R, \sigma_r, \sigma_i) = (v_0, \psi_0, \theta_0, \phi_0, R_0, \sigma_{r0}, \sigma_{i0}) + \delta(v_1, \psi_1, \theta_1, \phi_1, R_1, \sigma_{r1}, \sigma_{i1}) + \dots \quad (9)$$

Using (9) in the system for the z -dependent coefficients, we solve the resulting systems in the orders $1/\delta$, δ^0 and δ^1 to determine the main stability results.

At order $1/\delta$ we find

$$\sigma_{r0} = \sigma_{i0} = 0 \quad (10)$$

At order δ^0 we find the leading order eigensolutions to be

$$v_0 = [(\pi^2 + a^2)/(R_0 a^2 G)] \sin(\pi z), \quad (11a)$$

$$\psi_0 = T\pi [(\pi^2 + a^2)/(R_0 a^2 G)] \cos(\pi z), \quad (11b)$$

$$\theta_0 = -\sin(\pi z), \quad (11c)$$

$$\phi_0 = \left\{ -\pi(\pi^2 + a^2)/(CG[(\sigma_{r1} + i\sigma_{i1})^2 + \pi^2]) \right\} \left\{ [(\sigma_{r1} + i\sigma_{i1})/\pi] \sin(\pi z) + \cos(\pi z) + \exp[(\sigma_{r1} + i\sigma_{i1})(z - 1)] \right\}, \quad (11d)$$

$$R_0^2 = (\pi^2 + a^2)[(\pi^2 + a^2) + \pi^2 T^2]/(a^2 G), \quad (11e)$$

where $a = |a|$.

If we restrict ourselves to the solutions up to and including order δ^0 , then R_0 is minimized with respect to a to yield

$$R_{0c} = \pi [1 + (1 + T^2)^{1/2}] / \sqrt{G}, \quad (12a)$$

$$a_{0c} = \pi (1 + T^2)^{1/4}, \quad (12b)$$

where R_{0c} is the minimum value of R_0 achieved at $a = a_{0c}$.

At order δ we find the simplified system for v_1 and θ_1 after eliminating ψ_1 and ϕ_1 between all the four equations. We then multiply the equation for v_1 by $Ga^2 v_0$ and the equation for θ_1 by θ_0 , add the resulting equations, integrate over the fluid layer and make use of the boundary conditions. The result is a complex equation whose real and imaginary parts for the neutrally stable flow case, where $\sigma_{r1} = 0$, yield

$$(R_l/R_0)=[K_l/(4C)][(\pi^2+a^2-\pi^2T^2)/(\pi^2+a^2+\pi^2T^2)]+\pi^2T^2/[2C(\pi^2+a^2+\pi^2T^2)]+GG_l\{1/4+\pi^2[1+\cos(\sigma_{i1})]/(\pi^2-\sigma_{i1}^2)^2\}, \quad (13a)$$

$$\sigma_{i1}\{1+G_l[(\pi^2+a^2)/(\pi^2-\sigma_{i1}^2)][1-2\pi^2\sin\sigma_{i1}/(\sigma_{i1}\pi^2-\sigma_{i1}^3)]+L(\pi^2+a^2)^2[\pi^2(1-T^2)+a^2]/(R_0Ga)^2\}=0, \quad (13b)$$

where $G_l=(G-1)/(CG^2)$. The expressions for ν_l , ψ_1 , θ_1 and ϕ_1 are generally lengthy and will not be given here.

4. Results and discussion

It can be seen from the equation (13a) that zero value of the frequency is always a solution of this equation, so that stationary mode of neutrally stable state is always a solution to the present problem. However, stationary solution does not carry the effect of the inertial term in the present problem since such inertial term is due to the time derivative term in the momentum-Darcy equation and vanishes for any stationary mode of the problem. To investigate the possibility for oscillatory instability, we need to look for solutions with non-zero frequency of (13b). In most of our presentation of the results in the present problem, we consider the dependence of the solutions based on the physical parameters S and C rather than on the composite parameters G and G_l . Figure 1 presents the magnitude of the frequency of the critical oscillatory mode versus S in the neutrally stable regime, which corresponds to the lowest value of R , for $C=S$. Here the solid line, dotted line, dashed line and dash-dot-dot line correspond, respectively, to $T=L=0$, $T=L-0.04=0$, $T-2=L=0$ and $T-2=L-0.04=0$. The values of the magnitude of the frequency are independent with respect to G as can be seen from (13b). It can be seen from this figure that for $T=0$ the value of the magnitude of the frequency is smaller for $L=0.04$ as compared with the one for $L=0$, while for $T=2$ the value of such magnitude is larger for $L=0.04$ as compared with the one for $L=0$. The results of our more generated data for the frequency indicate that the higher value of the period of oscillation of the solution corresponds to the case with non-zero inertial effect if the rotation rate is sufficiently small, while the smaller period of oscillation corresponds to the case with non-zero inertial effect if the rotation rate is sufficiently large. In addition, we find that non-zero frequency is possible for all values of L only if T is sufficiently small. However, if, for example, $L \geq 0.1$, then no non-zero value of the frequency is possible for $T \geq 4$. Rotation was found to enhance the domain in (S, C) -plane for the oscillatory mode, while inertial effect reduces such domain. It should be noted that throughout this paper by the oscillatory mode we mean one that was detected first by Anderson and Worster (1996) in the absence of rotation and inertial effects.

As can be seen from (13b), both $+\sigma_{i1}$ and $-\sigma_{i1}$ are two solutions to the equation (13b) which correspond to the same value for R_l as can be found from (13a). These two modes are neutrally stable at the critical value R_c of the Rayleigh number. To determine

further the properties of the oscillatory mode at the onset of convection, we need to examine the expression for R_c given by

$$R_c = R_{0c} + \delta R_{1c} + O(\delta^2), \quad (14)$$

where R_{0c} is given by (12a), and R_{1c} is given by (13a), provided R_0 , a and σ_{i1} are replaced, respectively, by R_{0c} , given by (12a), a_{0c} , given by (12b), and σ_{i1} corresponding to the value $R=R_c$. It should be noted that in the expression (13a) for R_c , the second term in the right-hand-side, which contains the factor (T^2/C) , is due to the interaction between the leading term in the basic state of the local solid fraction and the Coriolis term in the momentum-Darcy equation. If this interaction term is not taken into account, then we found that the value of R is reduced for the non-zero rotation case. Hence, presence of such interaction is stabilizing for the oscillatory flow in the linear regime.

It can be seen from (12a) and (13a) that the dependence of R_c on L is only indirectly through the dependence of the frequency on L . Figures 2a and 2b present R_c versus S for $T=0$ and $T=2$, respectively, and for $C=S$, $K_I=1.0$ and two different values of L . In each figure solid line corresponds to the case $L=0$ and the dashed line corresponds to $L=0.04$. Both figures are drawn for the same values of the frequency in the range $0.1 \leq \sigma_{i1} \leq 9.90$. It can be seen from both figures that rotation is stabilizing, while the flow destabilizes as S increases. Since S represents a measure of the latent heat relative to the heat content and C represents a measure of the difference in the characteristic composition of the solid-dendrite and liquid phases to the compositional variation of the liquid, the system is expected to destabilize as S increases or as C decreases. However, for the present case where $C=S$, it should be concluded that the destabilizing effect of S dominates the stabilizing effect of C in the present problem. It can be seen from the figure 2a that the inertial effect is slightly stabilizing especially for larger values of S , and it also tends to reduce the domain for the oscillatory mode. The result from the figure 2b indicates that the stabilizing effect of the inertial force is neutralized by the effect of rotation, while reduction of the oscillatory is increased further by the inertial force in the presence of rotation.

The results (12a) and (12b) for R_{0c} and a_{0c} and the fact that the critical values R_c and a_c for R and a can be in a small neighborhood about R_{0c} and a_{0c} , respectively, due to small deviation of R_0 from R , indicate that the critical values R_c and a_c increase with T . Hence, presence of the rotational constraint exerts stabilizing effect on the oscillatory mode at the onset of convection since R_{0c} increases with T . Also, the rotational constraint through the Coriolis force reduces the wavelength of the preferred flow since a_c increases with T .

We also examined the vertical distribution of the perturbation to the solid fraction ϕ [$\phi_0 + \delta\phi_1 + O(\delta^2)$] for the oscillatory mode at $C=S$. Some results are presented in Figure 3 for the vertical distribution of the perturbation to the solid fraction, which can provide information for the tendency for chimney formation in the mushy zone if the value of ϕ is negative, while tendency for the enhancement of the solid structure in the porous medium follows if the value of ϕ is positive. For this figures, $\delta=0.2$, $K_I=1.0$ and the

value of 0.01 for the amplitude of the perturbation quantities is chosen. The figure 3 presents the results for ϕ versus z for $x = y = t = 0$. Solid line corresponds to $T=L=0$ and $C=0.357$. Dotted line corresponds to $T=2, L=0$ and $C=0.343$. Dashed line corresponds to $T=0, L=0.04$ and $C=0.356$. Dash-dot-dot line corresponds to $T=2, L=0.04$ and $C=0.368$. It can be seen from this figure that for the inertial and rotating case ϕ is less negative as compared with the other cases, and its magnitude is smaller than that for the non-rotating counterpart over the lower-half of the layer. In addition, average value of $|\phi|$ over the vertical depth of the layer for the inertial and rotating case is smaller than the one for its non-rotating counterpart. In addition, our generated data for the oscillatory mode at a later time $t = 3\pi / (2|\sigma_{11}|)$ indicated that ϕ is positive everywhere, and its vertical-average value for the rotating case is larger than the one for the non-rotating counterpart. An important result uncovered by our calculated data for ϕ , such as the one presented in the figure 3, is that the vertical average of the of the perturbation to the solid fraction for the oscillatory mode is less negative for the rotating and inertial cases. Hence, industrial crystal growers may find such result useful in growing higher quality alloy crystals.

Finally we present a review of the related work in R03, which was done in the absence of the inertial effects. Although the investigation presented in R03 was for both oscillatory and stationary modes, we focus our review here mostly on the oscillatory aspects of the work, which are related to the present work and need some updated discussion. In R03 the numerical calculation of the frequency was based on an equation of the form (13b) but for $L=0$. Such equation contains the number π , which is also a removable singular point of the equation, provided sufficient exact value for π is used in the calculation, while it tends to be a non-removable singularity if a less exact value, such as 3.14 is used for π . In R03 the approximate value of 3.14 was used for this number in the equation to numerically evaluate the frequency for given value of the composite parameter G_r . This approximate value of 3.14 for π was found to be satisfactory everywhere except for the cases of the value of the frequency close to π . For the cases where the value of the frequency is close to that of π , corresponding to values of G_r less than about 0.61 in the absence of rotation, sufficiently more exact value of π , such as 3.141592654, need to be used to numerically evaluate the frequency, as has been done in the present work. It turns out, in particular, that for $T=0$ case the minimum value of $G_r=0.5$ corresponds to the smallest value of the magnitude of the solution for the frequency if sufficiently exact value of π is used in the calculation for the frequency. It should, however, be noted that for the rotating case, the value of G_r can become less than 0.5 as was discussed accurately in R03, even if sufficiently accurate value for π is used in the calculation. If the value of 3.14 is used for π in the numerical evaluation of the frequency, then G_r can become smaller than 0.5 in the absence of rotation, and, in addition, more than one oscillatory mode may be generated as was detected in R03. One graph in the figure 1 in R03, which was for the case $G_r=0.2$, then need to be redrawn (see the solid line in Figure 4 of the present paper) since it is not expected to be accurate at least for $T=0$, even though the qualitative results presented in R03 for this figure remain unchanged. Figure 4 in the present paper shows frequency versus T for $G=2$ and $G_r=0.672$, where the solid and dashed lines correspond, respectively, to $L=0$ and 0.04. Frequency calculations in this paper are done based on the sufficiently exact value of π

($\pi=3.141592654$). We have chosen the value of 0.672 for G_t since it corresponds to value of 3.18 for the frequency in the absence of rotation, which is the same value for the frequency for $T=0$ used in the graph in the figure 1 of R03. Figure 4 in the present paper also shows the dashed-line graph for the frequency versus T for $L=0.04$. It can be seen from this graph that for the inertial case the period of the flow oscillation can be quite different from the one in the absence of the inertial effect. This figure also shows that for the given values of the parameters G and G_t , the period of the flow oscillation for $L=0.04$ is larger (smaller) than that for $L=0$ if $T<(>)T_1$, where T_1 is a value between 1.5 and 2. The graph for $L=0.04$ has apparently an asymptote for $T=T_2$, where T_2 is a value between 6 and 6.5. For $T>T_2$, there is no non-zero frequency for $L=0.04$, $G=2$ and $G_t=0.672$. After sufficiently exact value of π is used in the numerical evaluation of the analytical expressions, which were derived accurately in R03, our final statement about the non-inertial work in R03 is that the main qualitative results about the critical stationary mode, where $G=1$ and $G_t=0$, and the critical oscillatory mode, where $G>1$ and $[G_t(\pi^2+a^2)/(2\pi^2)]>0.61$, remain unchanged. This later condition on G_t is derived easily from a simple analogy between the rotating and non-rotating versions of (13b) and the fact that in the non-rotating and non-inertial case the non-zero frequency exists only if $G_t>0.5$ and the value of $\pi=3.14$ used in the calculation is satisfactory if $G_t>0.61$.

5. Conclusion

We investigated the problem of effect of inertial force on linear oscillatory flow instabilities in a horizontal dendrite layer during the alloy solidification and uniformly rotating about the vertical axis. The interaction between the local solid fraction and the flow associated with the Coriolis term in the momentum-Darcy equation is fully taken into account to determine the results. Over an extensive range of the parameter values, the inertial effect was found to reduce the domain for the presence of the oscillatory flow, while rotational effect enhances such domain. For sufficiently large rate of rotation and for given values of the other parameters no oscillatory flow is possible if inertial effect is present. Depending on the parameter values, there is a critical value of the rate of rotation below which the period of oscillation for the flow in the presence of the inertial effect is higher than that in the absence of the inertial force, while for the rate of rotation above its critical value the period of oscillation in the presence of inertial effect is smaller than that in the absence of the inertial effect. The oscillatory mode was found to be able to reduce the tendency for the chimney formation in the rotating dendrite layer.

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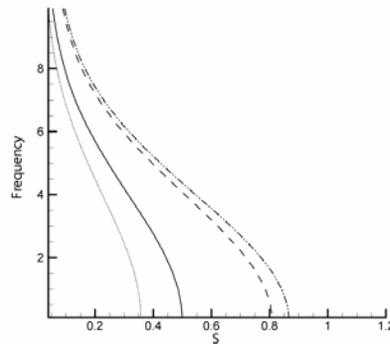


Figure 1. Frequency versus S for $C=S$. Here solid line, dashed line, dotted line and dash-dot-dot line present, respectively, the cases of $T=L=0$, $T-2=L=0$, $T=L-0.04=0$ and $T-2=L-0.04=0$.

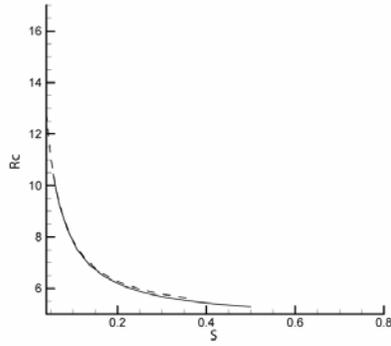


Figure 2a. R_c versus S for $C=S$, $K_I=1$ and $T=0$. Here solid and dashed lines present, respectively, the cases of $L=0$ and 0.04 .

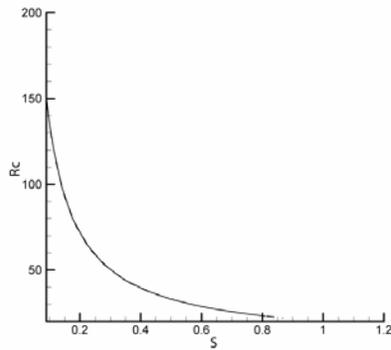


Figure 2b. The same as in the figure 2a but for $T=2$.

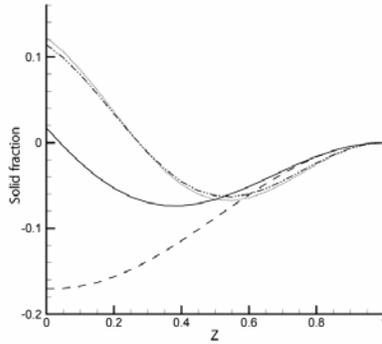


Figure 3. Perturbation to solid fraction versus z for $x=y=t=0.0$ and $S=C$. Here solid, dotted, dashed and dash-dot-dot lines present, respectively, the cases of $T=L=C-0.357=0$, $T-2=L=C-0.343=0$, $T=L-0.04=C-0.356=0$ and $T-2=L-0.04=C-0.368=0$.

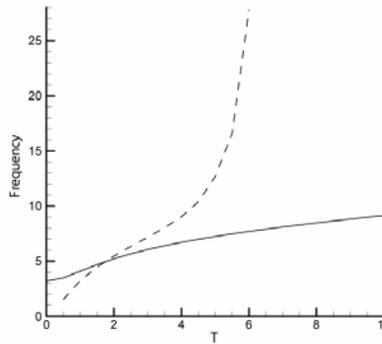


Figure 4. R_c versus T for $G=2$, $G_l=0.672$ and $K_l=1$. Here solid and dashed lines present, respectively, the cases of $L=0$ and 0.04 .

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